

Fig. 2 is a bottom view of the slicer of Fig. 1, with part of the slicer removed to reveal part of the belt tensioning device of the present invention;

Fig. 3 is a partial cutaway bottom view of the slicer of Fig. 1, showing part of the belt tensioning device of the present invention;

Fig. 4 is a schematic representation of the belt tensioning device of the present invention, shown in an un-tensioned state;

Fig. 5 is a schematic representation of the device of Fig. 3, shown in a fully tensioned state;

Fig. 6 is a schematic representation of the belt tensioning device of the present invention shown in an alternate location and in its fully tensioned state;

Fig. 7 is an alternate embodiment of the belt tensioning device of the present invention shown in its un-tensioned state; and

Fig. 8 is a perspective, partial cutaway view of a mixer including the belt tensioning device of the present invention.

Amend the second full paragraph of page 4 such that it reads as follows:

In an alternate embodiment, the arm 32 may comprise a variety of lever arms (not shown) to change the leverage of the arm 32 on the rotation of the motor 20 (and thereby optimize the force on the belt 30), or to change the moment arm ratios in the system. Furthermore, a variety of lever arms may be used to change the rotation of the motor 20; that is, a lever arm may be provided to rotate the motor in the opposite direction of arrow **A** when the nut 42 is tightened down.